# Linklt Smart 7688

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Linklt<sup>TM</sup> Smart 7688 (a compact controller board) is an open development board, based on the OpenWrt Linux distribution and MT7688 (datasheet



(http://www.seeedstudio.com/wiki/images/9/90/MT7688\_datasheet.pdf) ). The board is designed especially for the prototyping of Rich Application IoT devices for Smart-Home<sup>[1]</sup>. The board offers sufficient memory and storage to enable robust video processing. The platform also offers options to create device applications in Python, Node.js and C programming languages.

<sup>[1]</sup>This board is only a part of MediaTek LinkIt<sup>TM</sup> Smart 7688 platform which includes other development boards.

**Note:** This page only guides you to get started with this development board. For a complete guide, please refer to Resources (http://www.seeedstudio.com/wiki/Linklt\_Smart\_7688#Resources).



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## **Features**

- Single input single output (1T1R) Wi-Fi 802.11 b/g/n.
- Pin-out for GPIO, I<sup>2</sup>C, I<sup>2</sup>S, SPI, UART, PWM and Ethernet Port.
- 580 MHz MIPS CPU.
- 32MB Flash and 128MB DDR2 RAM.
- USB host.
- Micro SD slot.

# **Application ideas**

- Rich application IoT Devices for Smart-Home
- Robotics

# **Specification**

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Category	Feature	Specification	
	Chipset	MT7688AN	
	Core	MIPS24KEc	
MPU	Clock speed	580MHz	
	Working voltage	3.3V	
PCB Size Dimensions 55.7 x		55.7 x 26 mm	
N.4	Flash	32MB	
Memory	RAM	128MB DDR2	
Dannan Cannaa	USB Power	5V (USB micro-B)	
Power Source	VCC	3.3V (Pin Breakout)	
CNO	Pin Count	22 (MT7688AN)	
GPIO	Voltage	3.3V	
	Pin Count	4 (MT7688AN)	
	Voltage	3.3V	
	Max. Resolution	7 bits (customizable)	
PWM	Maximum Frequency@Resolution	100kHz@1-bit, 50kHz@2-bit, 25kHz@3-bit, 12.5kHz@4-bit, 6.25kHz@5-bit, 3.125kHz@6-bit, 1.5625kHz@7-bit (Standard mode) 40MHz@1-bit, 20MHz@2-bit, 10MHz@3-bit, 5MHz@4-bit, 2.5MHz@5-bit, 1.25Mhz@6-bit, 625kHz@7-bit (Fast mode)	
External Interrupts	Pin Count	22 (MT7688AN)	
	Set count	1 (MT7688AN)	
SPI	Pin numbers	P22, P23, P24 (Shared with on-board flash), P25	
	Max. Speed	25 MHz	
	Set count	1 (MT7688AN)	
SPI Slave	Pin numbers	P28, P29, P30, P31	
	Max. Speed	25 MHz	
120	Set count	1 (MT7688AN)	
1-2	Pin numbers	P10, P11, P12, P13	
	Set count	1	
l <sup>2</sup> C	Pin numbers	P20, P21	
	Speed	120K/400K	
	Set count	3 (MT7688AN)	
UART Lite	Pin numbers	P8, P9, P16, P17, P18, P19	
	Max. Speed	0.5Mbps	
	Set count	1 (MT7688AN)	

	Speed	Micro-AB	
ICommunication	Wi-Fi	1T1R 802.11 b/g/n (2.4G)	
	Ethernet	1-port 10/100 FE PHY	
	Pin numbers	P2, P3, P4, P5	
User Storage	SD Card	Micro SD SDXC	

## **Hardware Overview**



### Parts list

Parts name	Quantity
LinkIt <sup>TM</sup> Smart 7688	1PC
Manual	1PC

# **Getting Started**

## Connect to the embedded operating system

**Note:** There are two ways described in the manual. Here, we only show the advanced way (using a USB to Serial adapter) which seems a little harder. But, you will benefit a lot from it in the long run.

#### **Materials required**

- Linklt Smart 7688 × 1
- USB cable (type A to micro type-B) × 2
- USB to Serial adapter × 1
- Jumper wires × 3

#### **On Windows**

1. Install PuTTY. PuTTY provides a system console environment using Secure Socket Shell (SSH) to access the development board's operating system.

2. Install Bonjour (https://support.apple.com/kb/DL999?viewlocale=en\_US&locale=en\_US) Print Service (For Windows 7, Windows 8, Windows 10)

3. Install driver. If you are using a USB cable based on FTDI chip, please download and install its driver from here (http://www.ftdichip.com/Drivers/VCP.htm). If you are having problems with the latest driver, try installing an older version (http://www.ftdichip.com/Support/Documents/InstallGuides.htm).

4. Next, connect the Serial to USB cable to LinkIt Smart 7688's pins as following table shows:

Pin on USB adapter	Corresponding Pin to be connected on LinkIt Smart 7688
Pin RX	Pin 8
Pin TX	Pin 9
Pin GND	Pin GND



5. After connecting the Serial to USB cable, open the device manager and notice the COM port number as

shown below. This number may vary on different computers.



6. Launch the PuTTY terminal and enter the COM port number of the USB device found in the device manager, click on the Serial radio button, type 57600 in Speed box and click Open, as shown below.

ategory:		
Session Logging Terminal Keyboard Bell Features Window Appearance Behaviour Translation Selection Colours Connection Data Proxy Telnet Blogin	Basic options for your PuT Specify the destination you want to con Serial line COM9 Connection type: Raw Telnet Rlogin Load, save or delete a stored session Saved Sessions Default Settings	TY session nnect to 57600 SSH Seria Load Save
Serial	Close window on exit Always Never Onl	ly on clean exit

7. Now you will see printing text as those in a Linux console.

#### On Mac

1. Install the driver if needed. Check the cable manufacturer's website for driver requirements on Mac and installation instructions.

2. Plug-in the cable and connect the cable to LinkIt Smart 7688.

3. Open a Terminal session.

4. Type Is /dev/cu\* in the Terminal. You should see a list of devices. Look for something like cu.usbserial-XXXXXXXX where XXXXXXXX is usually a random identifier. This is the serial device used to access the system console. For example:

\$ls /dev/cu*	
/dev/cu.Bluetooth-Incoming-Port	
/dev/cu.Bluetooth-Modem	
/dev/cu.pablop-WirelessiAP	
/dev/cu.usbserial-A6YMCQBR	
5. Use the screen utility to connect to the serial port and set the baudrate to 57600. This is because the baudrate of the system console is 57600 by default. For example: \$screen /dev/cu.usbserial-XXXXXXXX 57600	
6. Now you should be connected to the system console. Press <b>Enter</b> key in the Terminal to bring up the prompt. You will notice that the prompt has become a different regular application, it is the LinkIt Smart 768 prompt and it looks like the following:	38
root@myLinkIt:/#	

\_\_\_\_\_

...!

7. You are ready to make changes to the LinkIt Smart 7688 system through this console.

#### **On Linux**

1. Install the driver if needed. Check the cable manufacturer's website for driver requirements on Linux and installation instructions.

2. Plug-in the cable and connect the cable to LinkIt Smart 7688.

3. Open a Terminal session.

4. Type **Is /dev/ttyUSB\*** in the Terminal. You should see a list of devices. Look for something like cu.usbserial-XXXXXXXX where XXXXXXXX is usually a random identifier. This is the serial device used to access the system console. For example:

¢ls /dev/ttyUSB↑	1
·	

5. Use the **screen** utility to connect to the serial port and set the baudrate to **57600**. This is because the baudrate of the system console is 57600 by default. For example:

\$sudo screen /dev/ttyUSB0 57600

6. Now you should be connected to the system console. Press ENTER in the Terminal to bring up the prompt. You'll notice that the prompt has become different from your OS X Terminal application, it is the LinkIt Smart 7688 prompt and it looks like the following:

root@myLinkIt:/#

7. You are ready to make changes to the LinkIt Smart 7688 system through this console.

### **Running the Blink example**

#### **Materials required**

- Linklt Smart 7688 × 1
- USB cable (type A to micro type-B) × 1
- USB to Serial adapter × 1
- Jumper wires × 3

#### **Get Blink to work**

1. Power up your board with a micro-USB cable (only connect the USB Power interface, not the USB Host interface).

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2. Launch PuTTy and connect to the system with USB to Serial adapter as shown in the previous

 $(http://www.seeedstudio.com/wiki/LinkIt\_Smart\_7688 \# Connect\_to\_the\_embedded\_operating\_system) \ section.$ 

3. Type python /IoT/examples/blink-gpio44.py and press Enter to run the Blink example.

4. Notice that the Wi-Fi LED blinks steadily.

5. In the system console, type CTRL + C, this will terminate the example.

### **Connect to the Internet (Switch to Station mode)**

There are two Wi-Fi modes, i.e. AP mode and Station mode. Refer this (https://answers.yahoo.com/question/index? qid=20061207225409AANCN17) for the differences between them.

1. Power up the board with a micro-USB cable.

2. Open the Wi-Fi connection utility on your computer and connect to the access point named LinkIt Smart 7688 XXXXXX. **XXXXXX** is a kind of hardware identifier which varies from board to board.

1top

Currently connected to: mediatek.inc Internet access	\$ <del>1</del>
Dial-up and VPN	•
	<i>i</i>
	~
mtkemp	Connected
mtkcs	lte.
mtkguest	<b>3</b> 41
LinkIt_Smart_7688_1B09F3	<u>.</u>
Information sent over this network m others.	ight be visible to
Connect automatically	Connect +
Open Network and Sharing	Center

3. Open a browser with URL **mylinkit.local/** or **192.168.100.1**, set the password for root and sign in. Click **Network** on the upper right.

Welcome to MediaTek Linklt Smart 7688

For advanced network configuration, go to OpenWrt.

	Network
Platform information	
Device name	
mylinkit	
Current IP address	
192.168.100.1	
Account information	
Account	
root(default)	
Password*	
•••••	
CONFIGU	IRE

4. Select the **Station mode** and click **Refresh** or downward arrow on the right to find the AP to connect to. After you have selected the AP, enter password if required. Click Configure & Restart to finish as shown below. Then wait for around 30 seconds to switch mode.

MEDIATEK	English 🎽 Sign out
Welcome to MediaTek Linklt Smart 7688	For advanced network configuration, go to OpenWrt.
System information	Network
Network setting	
O AP mode 💿	Station mode
Detected Wi-Finetwork* mtkemp (83%)	
REFRESH	
Password	
SHOW PASSWORD	
CANCEL	CONFIGURE & RESTART

- 5. Launch PuTTy and connect to the system with USB to Serial adapter as shown in the previous section.
- 6. Type **ifconfig** and find the IP address of **inet addr** as shown below:

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**Note:** It will still enter the Station mode after rebooting the system. Press wi-fi button at least 5 seconds to switch back to AP mode. **Note:** It will be needed to reboot the embedded OS by using **reboot** command.

7. Type the IP in a new Tab of browser and you can login to Web user interface to configure the system.
8. Now both the host computer and LinkIt Smart 7688 are connected to internet. Type ping
www.mediatek.com in console and you will get:

```
root@myLinkIt:/# ping www.mediatek.com
PING www.mediatek.com (175.98.146.37): 56 data bytes
64 bytes from 175.98.146.37: seq=0 ttl=245 time=39.076 ms
64 bytes from 175.98.146.37: seq=1 ttl=245 time=38.717 ms
64 bytes from 175.98.146.37: seq=2 ttl=245 time=39.250 ms
64 bytes from 175.98.146.37: seq=3 ttl=245 time=118.304 ms
64 bytes from 175.98.146.37: seq=4 ttl=245 time=118.949 ms
```

9. Now you can use internet to configure your system on development board.

## Demo: A Hello world example

**Note:** To avoid running out of memory during native application development, you should set up the native application development environment in a more powerful host environment that enables you to cross-compile the executable format of the LinkIt Smart 7688 target instead. The following table shows an overview of the LinkIt Smart 7688 programming languages and their related development environment on host computer.

Programming language	Tools and libraries	Applications	Host platforms supported
C/C++	Cross compilation	System	OS X
	toolchain	programming	Linux
Python	Python runtime on Linklt Smart 7688	Prototyping Network Arduino bridge library	OS X Linux Windows
Node.js	Node.js runtime on	Prototyping	OS X
	Linklt Smart 7688	Network	Linux Windows

### A Hello world example in Python

1. Use FileZilla and refer to this tutorial (https://wiki.filezilla-project.org/FileZilla\_Client\_Tutorial\_(en)) to know

how to connect with server or another host computer, the server IP (replace **host name**) address is the **inet addr** found in Switch to Station mode section

(http://www.seeedstudio.com/wiki/LinkIt\_Smart\_7688#Connect\_to\_the\_Internet\_.28Switch\_to\_Station\_mode.29) , the username is **root** and password is the password you set in that section.

2. Open a text editor, copy and paste the below example code and save it as **helloworld.py**.

print "Hello World!"

.....

- 3. Copy the file **helloworld.py** into system on target development environment (LinkIt Smart 7688) with FileZilla, place it under the folder **root.**
- 4. Launch PuTTY and connect to system with USB to Serial adapter.
- 5. Set working directory to /root and enter python helloworld.py to execute.
- 6. Now you can see Hello World! printed in console.

## Resources

- Hardware Schematic files (http://www.seeedstudio.com/wiki/images/6/6e/Hardware\_Schematics.zip)
- Manual (http://www.seeedstudio.com/wiki/images/1/17/Manual.zip)
- OpenWrt (http://wiki.openwrt.org/doc/howto/user.beginner)
- Firmware\_upgrade\_Instruction (http://www.seeedstudio.com/wiki/File:LinkIt\_Smart\_7688\_Firmware\_upgrade.zip)

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